

# Low Load Certification Cycle

Public Workshop to Discuss Potential Changes  
to the Heavy-Duty Engine and Vehicle Emission  
Standards, Test Procedures, Warranty, and  
Other Related Heavy-Duty Programs

November 3, 2016  
Diamond Bar, California

California Environmental Protection Agency

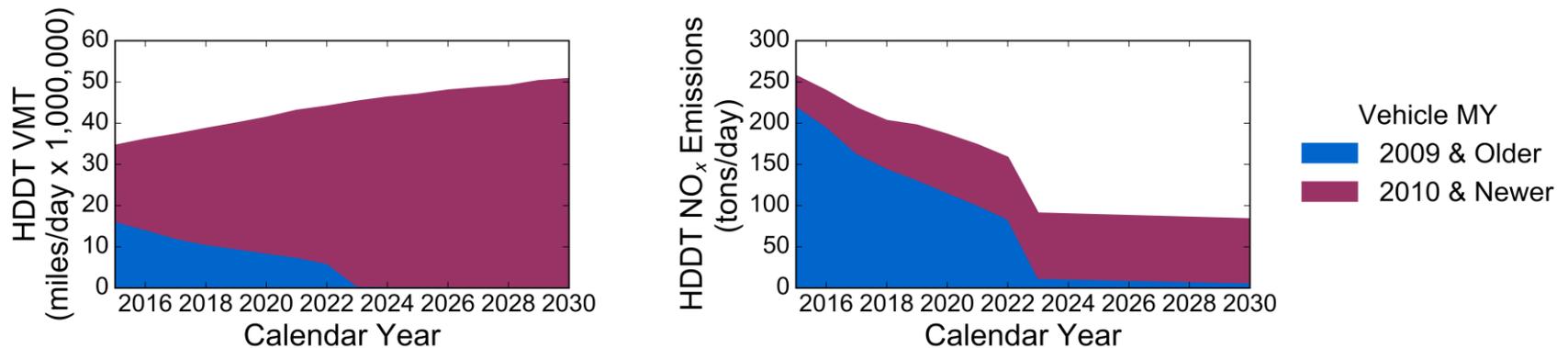
 **Air Resources Board**

# Outline

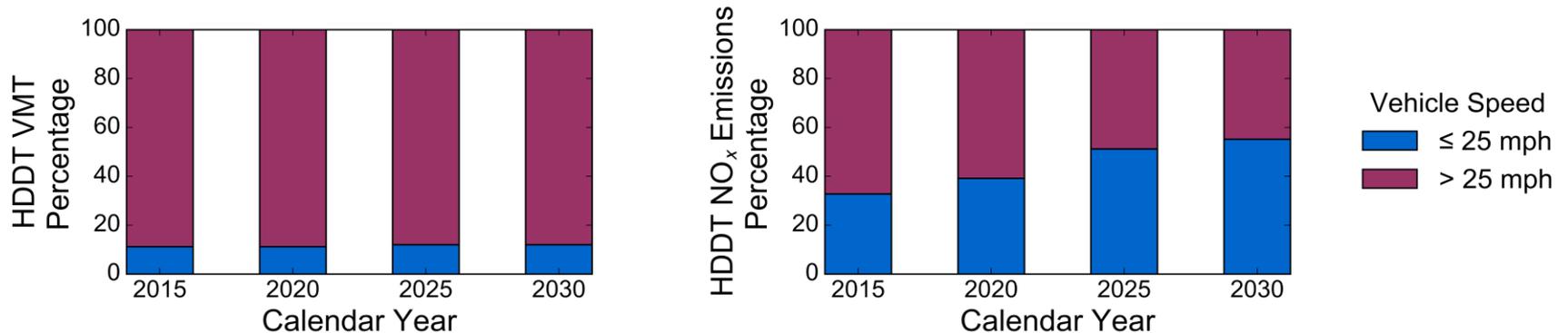
- ▶ Need for a Low Load Cycle (LLC)
  - Heavy-duty Diesel Truck (HDDT) NO<sub>x</sub> Emissions at Low Speeds
  - Shortcomings of Current Certification Cycles
- ▶ Engine Cycle Development Approach
  - Background on HD-FTP Development
- ▶ Strategy for Developing LLC
- ▶ Opportunity to Join Workgroup

# Low Load NO<sub>x</sub> Emissions from 2010+ MY HDDDTs

- ▶ VMT and NO<sub>x</sub> emissions from 2009 and older HDDDTs to decrease substantially by 2023



- ▶ NO<sub>x</sub> emissions from low-speed operation to become increasingly significant, due to SCR inefficiency at low loads



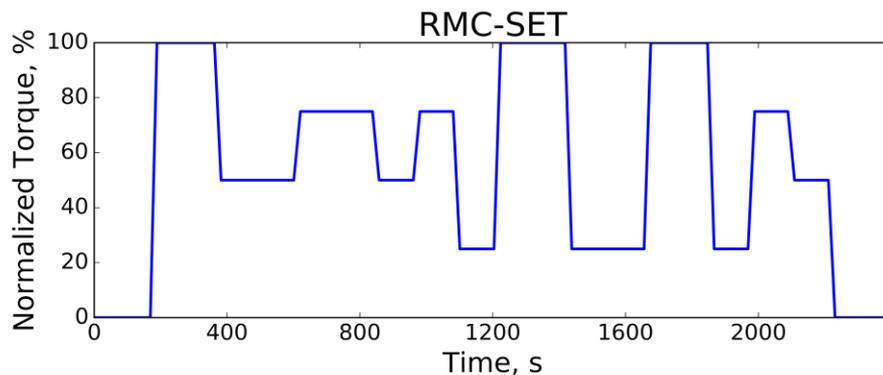
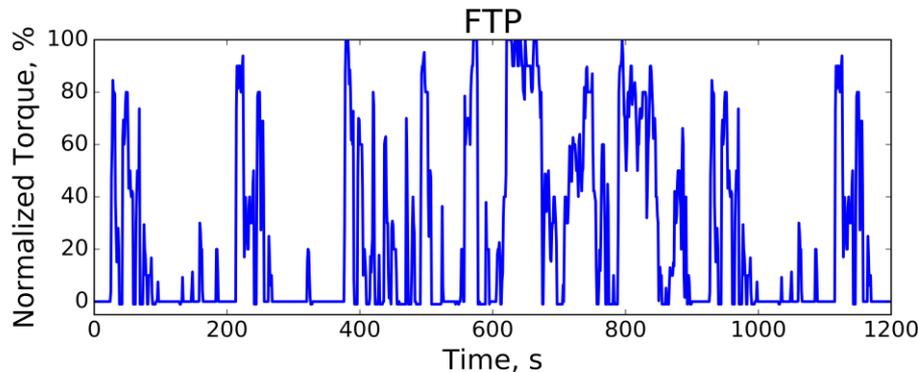
# Low Load NO<sub>x</sub> Emissions from 2010+ MY HDDTs

- ▶ In-use chassis dynamometer and PEMS on-road testing data\* show much higher NO<sub>x</sub> emissions from 2010+ MY HDDTs, compared to certification levels

Activity		Average Speed, mph	Emissions, g/bhp-hr	Certification Level, g/bhp-hr
Cycle	Drayage- Near Dock	6.8	1.80	0.12
	Drayage- Local	9.3	1.18	0.12
	Drayage- Regional	24	0.36	0.12
	UDDS	19	0.34-0.88	0.11-0.12
On-Road	Urban	26	0.32-0.97	0.11-0.13
	Rural	40	0.17-0.41	0.11-0.13

\* S. Yoon, J.F. Collins, C. Misra, J.D. Herner, M.W. Carter, T.P. Sax, "High In-Use NO<sub>x</sub> Emissions from Heavy-Duty Trucks Equipped with SCR Systems and Their Impact on Air Quality Planning in California", to be presented at 2017 Transportation Research Board Meeting.

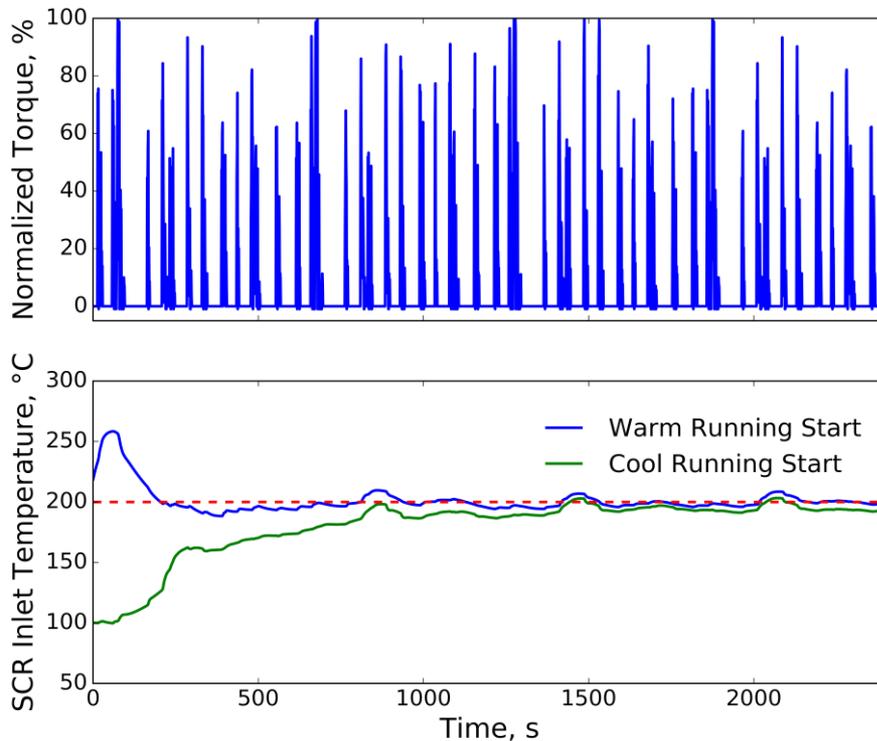
# Shortcomings of Current Certification Cycles: HD-FTP and RMC/SET



- ▶ HD-FTP and RMC/SET cycles do not account for sustained low load operations
- ▶ HD-FTP is not of sufficient length to verify active thermal management of SCR systems
- ▶ HD-FTP was developed in 1970's:
  - Real-world vehicle and engine activities nowadays might be markedly different
  - Methods used then to estimate engine load factors were not of high accuracy

# Shortcomings of Current Certification Cycles

- ▶ Vocational cycles typically exhibit significantly lower exhaust temperatures
- ▶ Example: New York Bus Cycle\* (NYBC)



SCR inlet temperature consistently under 200°C, even under warm start

NO<sub>x</sub> Emission:

0.55 g/bhp-hr (warm running start)

2.35 g/bhp-hr (cool running start)

\* <https://www.arb.ca.gov/research/veh-emissions/low-nox/low-nox.htm>

# New Low-Load Engine Cycle

- ▶ Objective is to develop a new HD engine test cycle that:
  - Represents real-world urban tractor and vocational vehicle operations, characterized by low engine loads
  - Is of sufficient length such that continuous active thermal management is required
  - Has an emission standard that balances the need for NO<sub>x</sub> emission reductions and GHG emission impacts

# Engine Test Cycle Development– General Approach

- ▶ Typical steps of development process:
  1. Collection of real–world activity data
  2. Construction of candidate cycles using appropriately selected methodology
  3. Evaluation and selection of final cycle, based on its level of representativeness using statistical target parameters such as average speed, acceleration and deceleration, stops per unit distance, kinetic energy, maximum speed, kinetic intensity, etc.

# Engine Test Cycle Construction Methodologies

▶ An engine cycle can be constructed from:

1. In-use engine activity data directly, either

- Point-by-point, through random sampling that relies on a stochastic model to account for probability of successive transitions, or
- Linking divided activity segments (“microtrip” data, defined as stop-to-stop travel), that are selected at random

2. Chassis dynamometer testing:

Chassis cycle is first constructed from in-use vehicle speed data, then translated to corresponding engine cycle through chassis dynamometer testing of representative vehicles

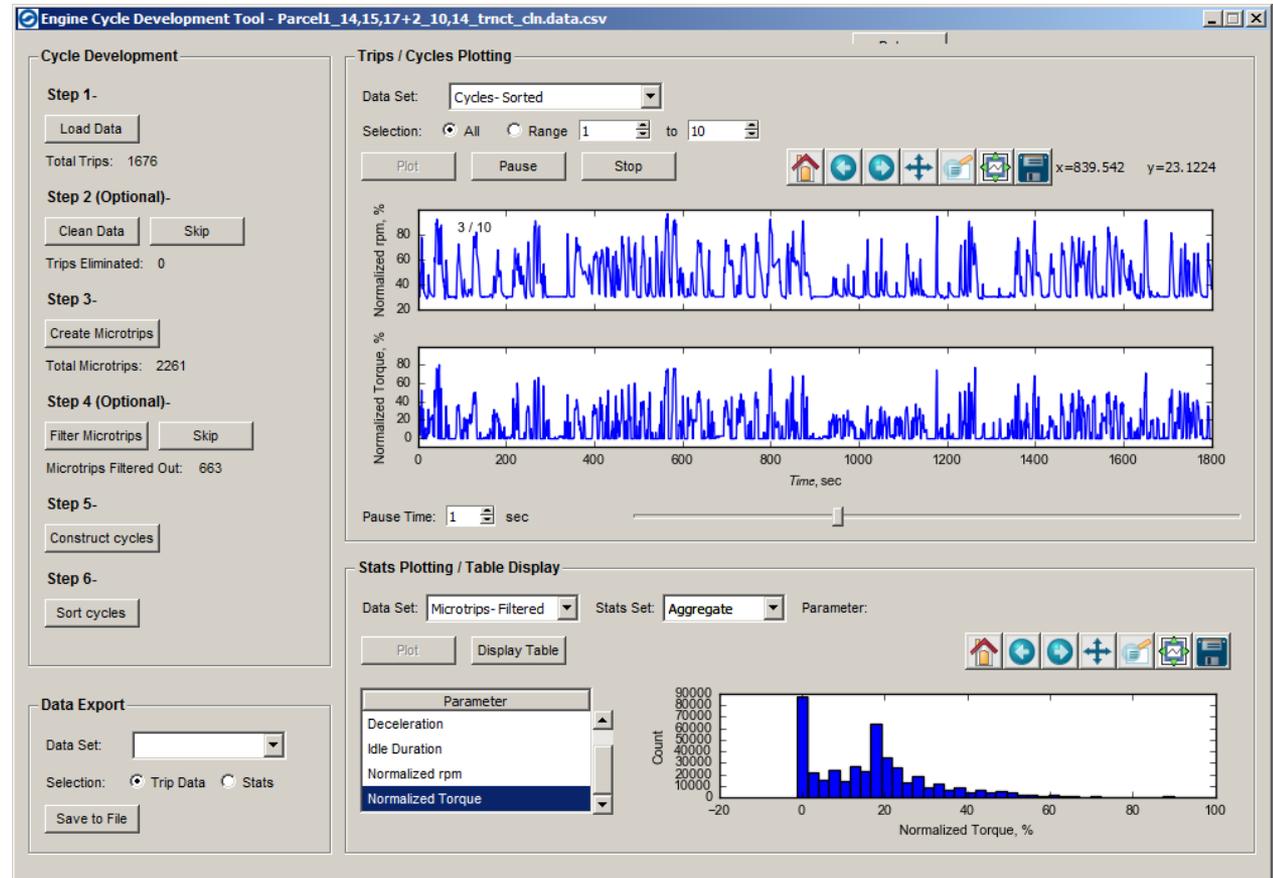
# Development of HD-FTP

- ▶ Developed, along with HD-UDDS, in late 70's from in-use data for 44 trucks and 4 buses in NY, and 44 trucks and 3 buses in LA
- ▶ Consists of four 5 minutes segments corresponding to NY non-freeway, LA non-freeway, LA freeway, and NY non-freeway operations
- ▶ Engine load factor estimated based on manifold vacuum for gasoline engines, rack position or rail pressure for diesel engines
- ▶ Cycle constructed by randomly sampling individual engine speed/load points, using Markov Chain model to describe likelihood of successive transitions

# Engine Cycle Development Tool

Tool developed by ARB staff with following capabilities:

- Statistical analysis and filtering of large amounts of activity data
- Development of custom representative engine cycles directly from in-use engine activity data, with approach similar to that used in FTP development



# Low Load Cycle Development Plan

- ▶ ARB staff will work with SwRI/NREL to develop the low load cycle
- ▶ Activity data from following projects will be utilized:
  - Collection of Activity Data from On-Road Heavy-Duty Diesel Vehicles (UCR, completed 2016)
  - Data Collection, Testing, and Analysis of Hybrid Electric Trucks and Buses Operating in California Fleets (NREL, completed 2015)
  - Additional activity data collection projects sponsored by SCAQMD, EPA, etc

# Opportunity

- ▶ ARB requests vocational activity data from the HDV industry to supplement existing data for the low load cycle development
- ▶ HD CERTIFICATION STANDARDS AND TEST PROCEDURES WORKGROUP
  - Discuss policy and procedure
  - Share data on vocational engine/vehicle activity and methodology of developing test cycles

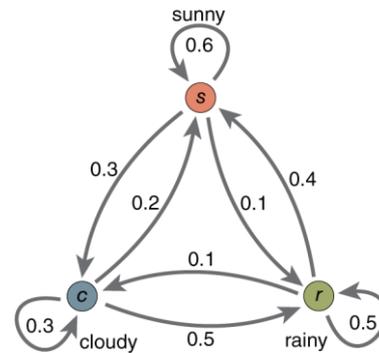
# Rulemaking Schedule/Contact

- ▶ Board Hearing: 2019
- ▶ More workshops through 2019
- ▶ Contact:
  - Lee Wang, Ph.D., P.E.
  - [lee.wang@arb.ca.gov](mailto:lee.wang@arb.ca.gov)
  - (626) 450-6145

# BACKUP SLIDES

# Markov Chains

- ▶ Markov Chain is a mathematical system that represents transition probabilities between states
- ▶ Example: weather states



- ▶ For engine data, the state at each point is defined by 4 parameters – speed, load, and changes in speed and load to next point